
pyEOF
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OVERVIEW

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**CHAPTER
ONE**

ABOUT

pyEOF is a **Python** package for **EOF** and Rotated EOF Analysis . It takes advantage of

- `sklearn.decomposition.PCA` (for EOF)
- `Advanced Principle Component Analysis` (for varimax rotation // varimax rotated EOF // REOF)

CHAPTER TWO

INSTALLATION

Step 1: create an environment:

```
$ conda create -n pyEOF python=3.7
$ conda activate pyEOF
$ conda install -c conda-forge numpy pandas scipy scikit-learn rpy2
```

Step 2: install using pip:

```
$ pip install pyEOF
```

(optional) for jupyter notebook tutorial:

```
$ conda install -c conda-forge numpy pandas scipy scikit-learn rpy2 xarray matplotlib
↪jupyter eof
```

(optional) install from source:

```
$ git clone https://github.com/zzheng93/pyEOF.git
$ cd pyEOF
$ python setup.py install
```

```
[1]: from pyEOF import *
import xarray as xr
import numpy as np
import pandas as pd
import matplotlib.pyplot as plt

# create a function for visualization convenience
def visualization(da, pcs, eof_da, evf):
    fig = plt.figure(figsize = (6,12))

    ax = fig.add_subplot(n+1,2,1)
    da.mean(dim=["lat","lon"]).plot(ax=ax)
    ax.set_title("average air temp")

    ax = fig.add_subplot(n+1,2,2)
    da.mean(dim="time").plot(ax=ax)
    ax.set_title("average air temp")

    for i in range(1,n+1):
        pc_i = pcs["PC"+str(i)].to_xarray()
        eof_i = eof_da.sel(EOF=i)[["air"]]
        frac = str(np.array(evf[i-1]*100).round(2))
```

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```
ax = fig.add_subplot(n+1, 2, i*2+1)
pc_i.plot(ax=ax)
ax.set_title("PC"+str(i)+" ("+frac+"%)")

ax = fig.add_subplot(n+1, 2, i*2+2)
eof_i.plot(ax=ax,
            vmin=-0.75, vmax=0.75, cmap="RdBu_r",
            cbar_kwarg={"label": ""})
ax.set_title("EOF"+str(i)+" ("+frac+"%)")

plt.tight_layout()
plt.show()

%matplotlib inline
/opt/anaconda3/envs/pyEOF/lib/python3.7/site-packages/rpy2/robjects/pandas2ri.py:14: FutureWarning: pandas.core.index is deprecated and will be removed in a future version. The public classes are available in the top-level namespace.
  from pandas.core.index import Index as PandasIndex
```

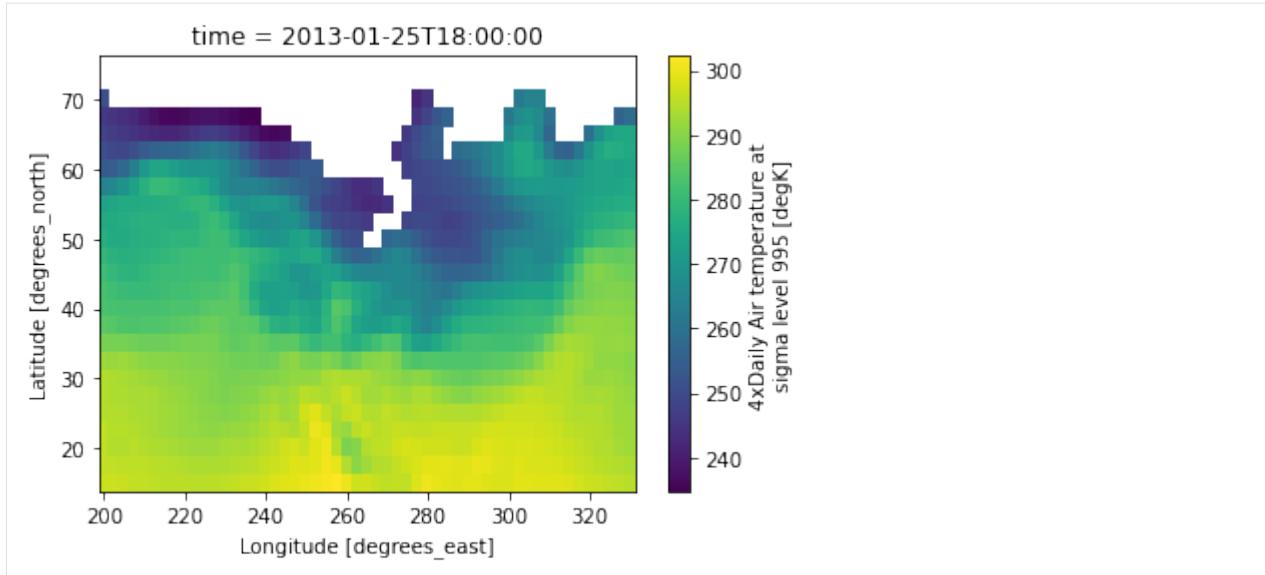
LOAD SAMPLE DATA

```
[2]: # load the DataArray
da = xr.tutorial.open_dataset('air_temperature')["air"]
print(da)

# create a mask
mask = da.sel(time=da.time[0])
mask = mask.where(mask<250).isnull().drop("time")

# get the DataArray with mask
da = da.where(mask)
da.sel(time=da.time[99]).plot()
plt.show()

<xarray.DataArray 'air' (time: 2920, lat: 25, lon: 53)>
[3869000 values with dtype=float32]
Coordinates:
 * lat      (lat) float32 75.0 72.5 70.0 67.5 65.0 ... 25.0 22.5 20.0 17.5 15.0
 * lon      (lon) float32 200.0 202.5 205.0 207.5 ... 322.5 325.0 327.5 330.0
 * time     (time) datetime64[ns] 2013-01-01 ... 2014-12-31T18:00:00
Attributes:
    long_name:        4xDaily Air temperature at sigma level 995
    units:            degK
    precision:       2
    GRIB_id:          11
    GRIB_name:        TMP
    var_desc:         Air temperature
    dataset:          NMC Reanalysis
    level_desc:       Surface
    statistic:        Individual Obs
    parent_stat:      Other
    actual_range:     [185.16 322.1 ]
```



```
[3]: # convert DataArray to DataFrame
df = da.to_dataframe().reset_index() # get df from da
display(df.head(5))
print("DataFrame Shape:", df.shape)

      time    lat    lon    air
0 2013-01-01  75.0  200.0   NaN
1 2013-01-01  75.0  202.5   NaN
2 2013-01-01  75.0  205.0   NaN
3 2013-01-01  75.0  207.5   NaN
4 2013-01-01  75.0  210.0   NaN

DataFrame Shape: (3869000, 4)
```

EOF ANALYSIS

4.1 reshape the dataframe to be [time, space]

```
[4]: df_data = get_time_space(df, time_dim = "time", lumped_space_dims = ["lat", "lon"])
display(df_data.head(5))
print("DataFrame Shape:", df_data.shape)
```

```
          air \
lat      75.0
lon     200.0 202.5 205.0 207.5 210.0 212.5 215.0 217.5 220.0
time
2013-01-01 00:00:00   NaN   NaN   NaN   NaN   NaN   NaN   NaN   NaN   NaN
2013-01-01 06:00:00   NaN   NaN   NaN   NaN   NaN   NaN   NaN   NaN   NaN
2013-01-01 12:00:00   NaN   NaN   NaN   NaN   NaN   NaN   NaN   NaN   NaN
2013-01-01 18:00:00   NaN   NaN   NaN   NaN   NaN   NaN   NaN   NaN   NaN
2013-01-02 00:00:00   NaN   NaN   NaN   NaN   NaN   NaN   NaN   NaN   NaN

          ...
          15.0 \
lat      ...
lon     222.5 307.5    310.0    312.5
time
2013-01-01 00:00:00   NaN   299.699982 299.100006 298.699982
2013-01-01 06:00:00   NaN   299.290009 298.600006 298.199982
2013-01-01 12:00:00   NaN   299.199982 298.699982 298.790009
2013-01-01 18:00:00   NaN   300.000000 299.399994 299.100006
2013-01-02 00:00:00   NaN   299.600006 299.000000 298.790009

          ...
          315.0 317.5 320.0 322.5 \
lat
lon
time
2013-01-01 00:00:00 298.600006 298.000000 297.790009 297.600006
2013-01-01 06:00:00 298.100006 297.500000 297.100006 296.899994
2013-01-01 12:00:00 298.699982 297.899994 297.899994 297.600006
2013-01-01 18:00:00 299.100006 298.500000 298.600006 298.199982
2013-01-02 00:00:00 299.000000 298.290009 298.100006 297.699982

          ...
          325.0 327.5 330.0 \
lat
lon
time
2013-01-01 00:00:00 296.899994 296.790009 296.600006
2013-01-01 06:00:00 296.399994 296.399994 296.600006
2013-01-01 12:00:00 297.000000 297.000000 296.790009
```

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```
2013-01-01 18:00:00 297.790009 298.000000 297.899994
2013-01-02 00:00:00 297.100006 297.399994 297.399994
```

```
[5 rows x 1325 columns]
```

```
DataFrame Shape: (2920, 1325)
```

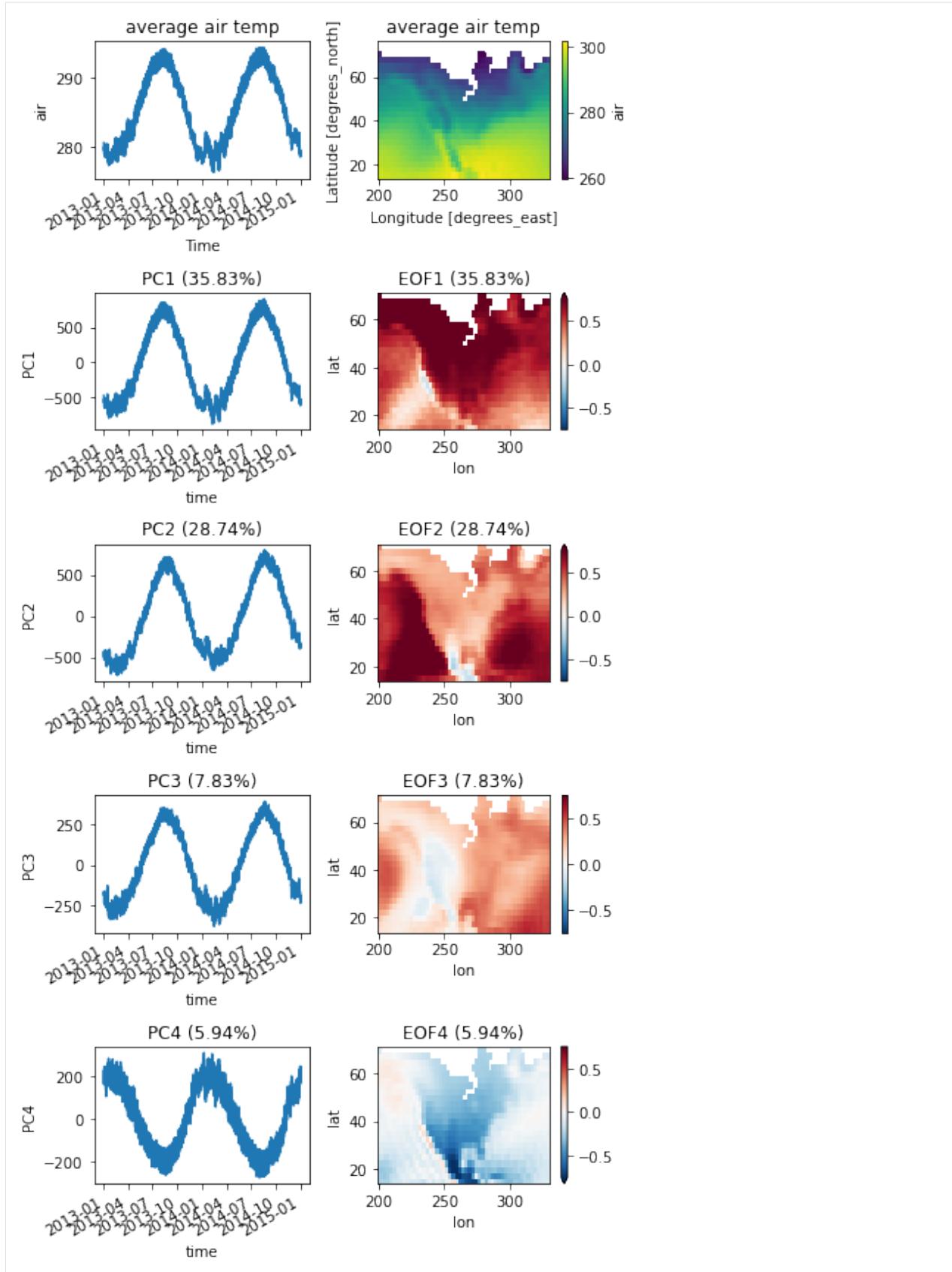
4.2 varimax rotated PCA analysis

```
[5]: n = 4
pca = df_eof(df_data,pca_type="varimax",n_components=n)

eofss = pca.eofss(s=2, n=n) # get eofss
eofss_da = eofss.stack(["lat","lon"]).to_xarray() # make it convenient for visualization
pcs = pca.pcs(s=2, n=n) # get pcs
evfs = pca.evf(n=n) # get variance fraction

# plot
visualization(da, pcs, eofss_da, evfs)

/opt/anaconda3/envs/pyEOF/lib/python3.7/site-packages/sklearn/utils/extmath.py:770:_
→RuntimeWarning: invalid value encountered in true_divide
    updated_mean = (last_sum + new_sum) / updated_sample_count
/opt/anaconda3/envs/pyEOF/lib/python3.7/site-packages/sklearn/utils/extmath.py:709:_
→RuntimeWarning: Degrees of freedom <= 0 for slice.
    result = op(x, *args, **kwargs, dtype=np.float64)
```



4.3 unrotated EOFs analysis

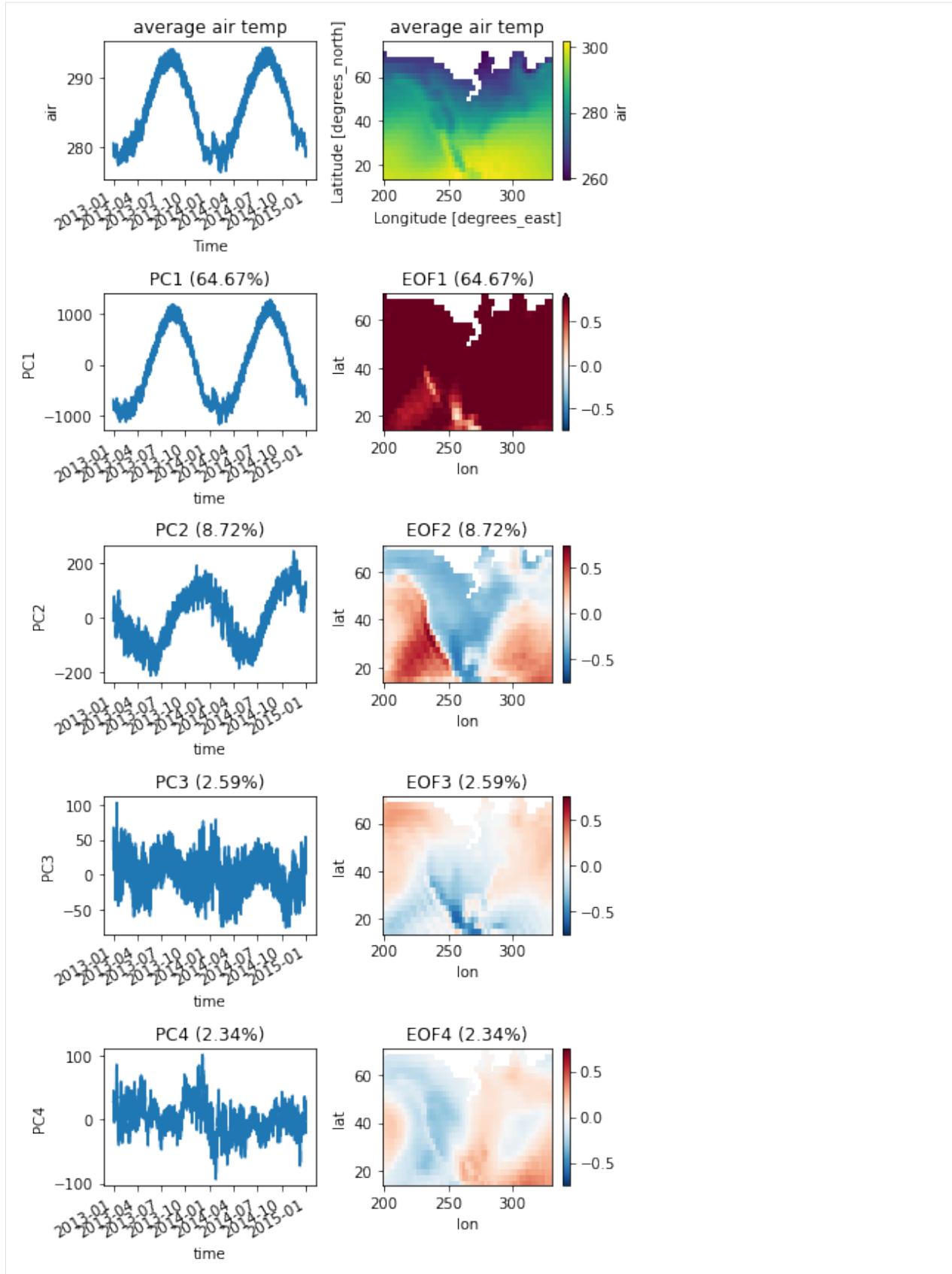
```
[6]: n = 4 # define the number of components

pca = df_eof(df_data) # implement EOF

eofss = pca.eofs(s=2, n=n) # get eofss
eofss_da = eofss.stack(["lat","lon"]).to_xarray() # make it convenient for visualization
pcss = pca.pcs(s=2, n=n) # get pcss
evfs = pca.evf(n=n) # get variance fraction

# plot
visualization(da, pcss, eofss_da, evfs)

/opt/anaconda3/envs/pyEOF/lib/python3.7/site-packages/sklearn/utils/extmath.py:770:_
    ↪RuntimeWarning: invalid value encountered in true_divide
    updated_mean = (last_sum + new_sum) / updated_sample_count
/opt/anaconda3/envs/pyEOF/lib/python3.7/site-packages/sklearn/utils/extmath.py:709:_
    ↪RuntimeWarning: Degrees of freedom <= 0 for slice.
    result = op(x, *args, **kwargs, dtype=np.float64)
```



COMPARE WITH EOFS PACKAGE (UNROTATED EOFS)

link: <https://ajdawson.github.io/eofs/latest/>

```
[7]: from eofs.standard import Eof
from sklearn.preprocessing import StandardScaler
solver = Eof(StandardScaler()).fit_transform(df_data.values)

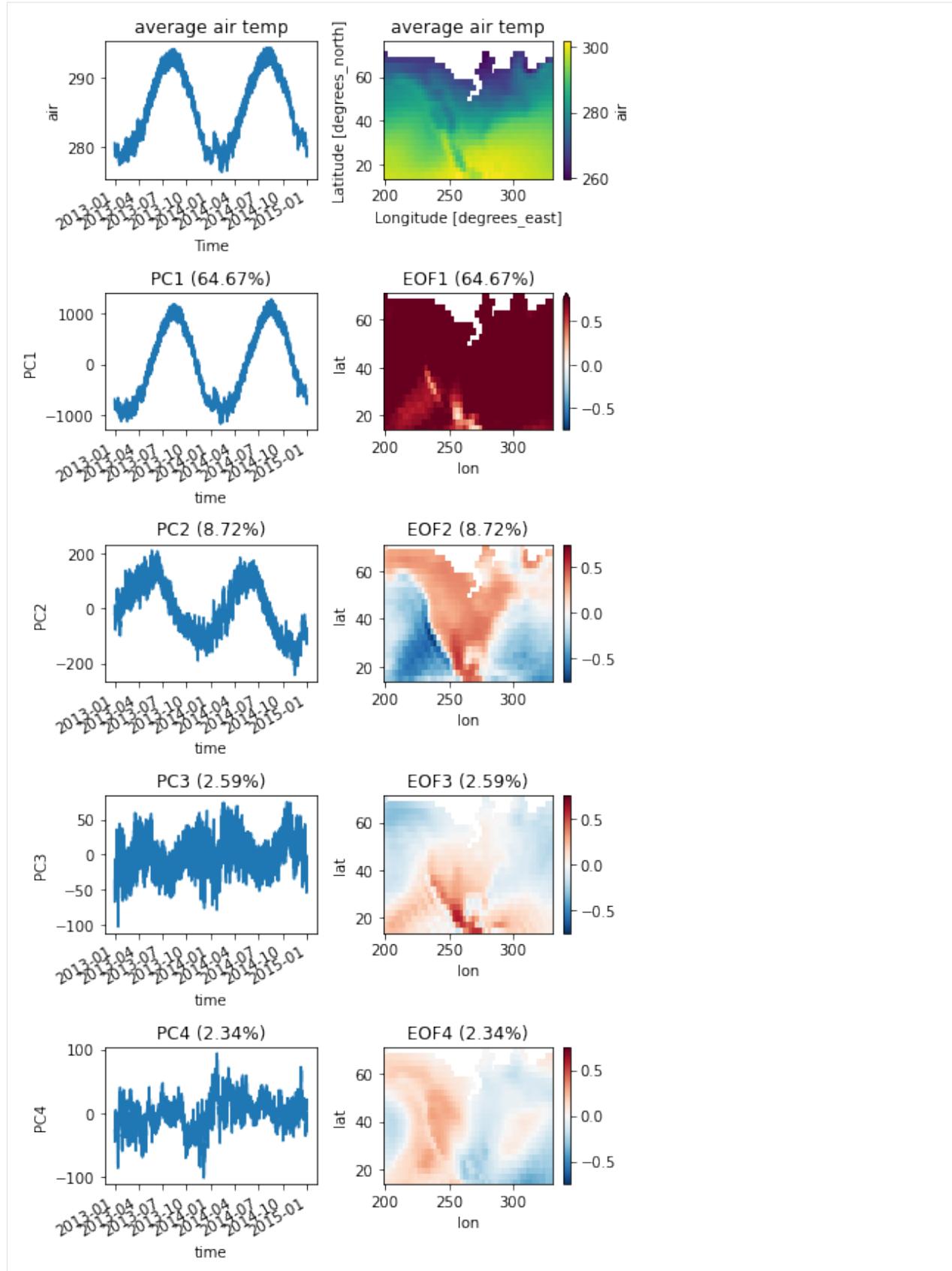
s_pcs = pd.DataFrame(data=solver.pcs(npcs=4, pcscaling=2),
                      columns = pcs.columns,
                      index = pcs.index)

s_eof = pd.DataFrame(data = solver.eof(neof=4, eofscaling=2),
                      columns = eof.columns,
                      index = eof.index)
s_eof_da = s_eof.stack(["lat","lon"]).to_xarray() # make it convenient for
→ visualization

s_evfs = solver.varianceFraction(neigs=4)

# plot
visualization(da, s_pcs, s_eof_da, s_evfs)

/opt/anaconda3/envs/pyEOF/lib/python3.7/site-packages/scikit-learn/utils/extmath.py:770:_
→RuntimeWarning: invalid value encountered in true_divide
    updated_mean = (last_sum + new_sum) / updated_sample_count
/opt/anaconda3/envs/pyEOF/lib/python3.7/site-packages/scikit-learn/utils/extmath.py:709:_
→RuntimeWarning: Degrees of freedom <= 0 for slice.
    result = op(x, *args, **kwargs, dtype=np.float64)
```



**CHAPTER
SIX**

HOW TO ASK FOR HELP

The GitHub issue tracker is the primary place for bug reports.